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**B.E. / B.TECH. DEGREE EXAMINATIONS, DEC 2019**

Seventh Semester

**EE16701 – SPECIAL ELECTRICAL MACHINES***(Electrical and Electronics Engineering)***(Regulation 2016)****Time: Three Hours****Maximum : 100 Marks**Answer **ALL** questions**PART A - (10 X 2 = 20 Marks)**

	<b>CO</b>	<b>RBT</b>
1. A stepper motor has a resolution of 900 steps/rev in the single phase ON mode of operation. If it is operated in half step mode, determine the number of steps required to turn the rotor to 72°.	<b>1</b>	<b>AP</b>
2. Enumerate the various types of driver circuits in stepper motor.	<b>1</b>	<b>R</b>
3. Compare Synchronous reluctance motor with Switched reluctance motor.	<b>2</b>	<b>AN</b>
4. Mention some applications of synchronous reluctance motor.	<b>2</b>	<b>U</b>
5. Outline the advantages of sensorless operation of Switched Reluctance Motor.	<b>3</b>	<b>AN</b>
6. Compute the step angle of a 3phase, Switched Reluctance Motor having 12 stator poles 8 rotor poles, also calculate commutation frequency at each phase and speed of 6000 rpm?	<b>3</b>	<b>AP</b>
7. Give examples of various permanent magnet materials.	<b>4</b>	<b>U</b>
8. Differentiate mechanical and electronic commutator.	<b>4</b>	<b>AN</b>
9. Mention the various types of rotor used in PMSM.	<b>5</b>	<b>R</b>
10. List out any four applications of PMSM.	<b>5</b>	<b>U</b>

**PART B - (5 X16 = 80 Marks)**

11. (a) Explain the construction, types and operation of VR stepper motor. **(16)** **1** **AP**  
List out the various modes of excitation and explain any one mode in detail.

**(OR)**

- (b) (i) State and explain the static characteristics of a stepper motor. **(8)** **1** **U**

- (ii) With neat block diagram, explain the microprocessor based control of stepping motor. **(8) 1 AP**
12. (a) Explain the constructions and working principle of axial and radial flux SyRM. **(16) 2 U**
- (OR)**
- (b) (i) Explain the phasor diagram of SyncRel motor. **(8) 2 AP**  
(ii) Explain the N-T and T-angle characteristics of SyncRel Motor. **(8) 2 AP**
13. (a) (i) Briefly discuss about the closed loop control of Switched Reluctance Motor. **(8) 3 U**  
(ii) Derive the voltage and torque equation of Switched Reluctance Motor. **(8) 3 AP**
- (OR)**
- (b) Enumerate various power converter circuits applicable to switched reluctance motor and describe with suitable diagram, the operation of any two power converter circuits. **(16) 3 U**
14. (a) From the magnetic circuit analysis of permanent magnet brushless DC motor, derive the expression for permeance coefficient. **(16) 4 AP**
- (OR)**
- (b) (i) Derive the EMF equation of a PMBLDC motor. **(6) 4 AP**  
(ii) Sketch the structure of controller for PMBLDC motor and explain the functions of various blocks. **(10) 4 U**
15. (a) (i) Explain the construction, working principle and operation of Permanent Magnet Synchronous Motor. **(16) 5 U**
- (OR)**
- (b) (i) Explain the torque - speed characteristics of Permanent Magnet Synchronous Motor. **(6) 5 U**  
(ii) Explain in detail the self control of Permanent Magnet Synchronous Motor. **(10) 5 U**