									Q. Code	e: 63	2980					
			Reg. No.									12. (a)	(i) A thermometer having a time constant	of		
										-			bath, Ti of 50°C and after the thermon	net		
			B. E / B. TECH.DEGREE			FION	5, MA	AY 202	23				bath, the temperature of the bath is sud	de		
		СН	Sixt 18603 –PROCESS INSTRUMI	h Semeste ENTATI		DVNA	MIC	'S & C	ONTRO)I.			of 0.25 min and bath is brought ba	.ck		
		CII		al Enginee				Juc					temperature of the thermometer.			
			×	lation 201	0/								(ii) Explain the response of a first order sys	te		
T	ME:	3 H	OURS]	MAX.	MARI	KS: 100				(0	DR		
C0 C0 C0 C0 C0	2 H 3 H 4 (Rela Desi Chec	sify the working principle and Industria te open loop and closed loop systems w gn controllers using open loop and close the stability of closed loop control sy over the advance control strategies and	with standa sed loop m vstem its implen	urd inp uethod mentat	out func s of tun tions in	ction ar	nd its re				(b)	The overall transfer function of the control sy $G(s) = \frac{16}{(1.5 s^2 + 2.4s+6)}$. A step change of system. Calculate. (i) Overshoot (ii) Period of Oscillation (iii) Ultimate value Y (t) (iv) Rise time			
			PART- A (Answer	(10x2=20 r all Quest		,							(iv) Rise time			
•					-					CO	RBT LEVEL	13. (a)	For the control system shown in the diagram.			
1.	Indi	cate	the objectives of chemical process co	ontrol with	1 suita	able exa	ample.			1	2		(1) Obtain the closed loop transfer C/U.			
2.	Indi	cate	the standard temperature scales with	their rang	ges.					1	3		(2) Evaluate the proportional gain for which	th		
3.	Writ	te do	the Laplace transform of $f(t) = e$	^{-2t} sin3t.						2	4		is 2.			
4.	Diff	feren	tiate between Interacting system and	Non Inter	acting	g syster	n.			2	2		(3) Find the offset for a unit step change in U	J if		
5.	Sket	tch t	he block diagram of feedback control	system a	nd lab	el the c	compo	onents.		3	3			_		
6.	Distinguish between servo and regulatory problem.						3	1			2					
7.	Show graphically the phase and gain margin.						4	4		(Zs + 1	1					
8.	State	tate phase margin and gain margin.					4	1		and the second						
9.	Indi	ndicate the digital form of PID control algorithm.				5	2			-						
10.	Nan	ne th	ne controlled variables in a control of	heat excha	anger.					5	1		(0	DR		
PART- B (5x 14=70Marks)				Marks	C) RBT	(b)	(i) Write the characteristic equation and co control system shown in fig. Is the syst								
11. (a) ((i)	Explain the principle and working of	of an optic	cal py	romete	er with	ı a neat		1	LEV EL 2		= 12.			
	((ii)	sketch. Write in detail the measurements of	humidity	of gas	ses.			(7)	1				1		
	(()		(OR)	8	-							R + SY LEI LA+			
(ł) ((i)	Explain the working of a bimeta		mome	eter ale	ong w	vith its	(7)	1	2					
, v	.,	(-)	material of construction and range of				-		(\cdot)	1	-		3	_		
	((ii)	With a neat sketch, explain the wo	1					(7)	1			3+3	_		

range of operation.

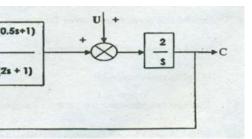
of 1 min is placed in a temperature	(10)	2	3
eter comes to equilibrium with the			
enly increased to 75°C for a period			
k to 50° C. Plot the response in			

er system to a step input.	(4)		3
(OR)			
rol system is given as	(14)	2	3
nge of magnitude 6 is introduced into the			

(14) 3 4

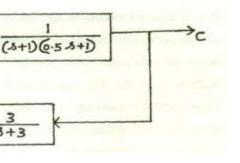
hich the closed loop damping coefficient

e in U if $K_c = 2$.



(OR)

nd construct the Routh array for the (10) 3 4 system stable for $K_c = 9.5$; $K_c = 11$; K_c



(ii) Compare pneumatic and electronic controller.

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4

14. (a) Sketch the bode diagram for the two first order system having time constant (14) 4 $\tau_1 = 10$ and $\tau_2 = 0.5$. A proportional controller with gain k_c is used to control the system. Assume the non-interacting first order system in series. $G(s) = K_c/(10s+1)(0.5s+1)$

(OR)

- (b) Explain in detail Z-N method of tuning, compare with Cohen-Coon method of (14) 4 4 tuning.
- 15. (a) With a neat schematic diagram, explain various control strategies used for (14) 5 2 terminal composition control in a binary distillation column.

(OR)

(b) Explain cascade control with examples. Derive the transfer function of for the (14) 5 2 cascade control system and discuss the advantages.

PART- C (1x 10=10Marks)

(Q.No.16 is compulsory)

		Marks	CO	RBT	
				LEVEL	
16.	There are N storage tanks of volume V arranged so that when water is fed	(10)	2	3	
	into the first tank, an equal volume of water overflows from the first tank				
	into the second tank, and so on. Each tank initially contains component A at				
	some concentration C_{o} and is equipped with a perfect stirrer. At time zero, a				
	stream of initial concentration is fed into the first tank at a volumetric rate				
	q. Find the resulting concentration in each tank as a function of time.				

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